

SONY

Diagonal 4.5mm (Type 1/4) Progressive Scan CCD Image Sensor with Square Pixel
for B/W Cameras

ICX618ALA

Description

The ICX618ALA is a diagonal 4.5mm (Type 1/4) interline CCD solid-state image sensor with a square pixel array which supports VGA format. Progressive scan enables all pixel signals to be output separately within approximately 1/60 second. This chip features an electronic shutter with variable charge-storage time which makes it possible to realize full-frame still images without a mechanical shutter. The sensitivity and near infrared sensitivity are improved drastically through the adoption of advanced EXview HAD CCD technology. This chip is suitable for applications such as security cameras and network cameras.

Features

- ◆ High sensitivity (+3.5dB compared with the ICX614ALA)
- ◆ High saturation signal (+2.0dB compared with the ICX614ALA)
- ◆ Low smear (−8.0dB compared with the ICX614ALA)
- ◆ Progressive scan enables individual readout of the image signals from all pixels.
- ◆ Square pixel
- ◆ Supports VGA format
- ◆ Horizontal drive frequency: Supports 24.54MHz
- ◆ No voltage adjustments (Reset gate and substrate bias need no adjustment.)
- ◆ High resolution, high sensitivity, low dark current
- ◆ Continuous variable-speed shutter
- ◆ Excellent anti-blooming characteristics
- ◆ Horizontal register: 3.3V drive
- ◆ 14-pin high accuracy plastic package (dual-surface reference available)

EXview HAD CCD™

* EXview HAD CCD is a trademark of Sony Corporation. The EXview HAD CCD is a CCD that drastically improves light efficiency by including near infrared light region as a basic structure of HAD (Hole-Accumulation Diode) sensor.

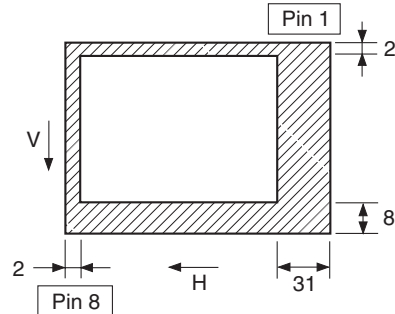
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Element Structure

- ◆ Interline CCD image sensor
- ◆ Image size
Diagonal 4.5mm (Type 1/4)
- ◆ Number of effective pixels
659 (H) × 494 (V) approx. 330K pixels
- ◆ Total number of pixels
692 (H) × 504 (V) approx. 350K pixels
- ◆ Chip size
4.46mm (H) × 3.80mm (V)
- ◆ Unit cell size
5.6μm (H) × 5.6μm (V)
- ◆ Optical black
Horizontal (H) direction: Front 2 pixels, rear 31 pixels
Vertical (V) direction: Front 8 pixels, rear 2 pixels
- ◆ Number of dummy bits
Horizontal: 16
Vertical: 4
- ◆ Substrate material
Silicon

Optical Black Position

(Top View)



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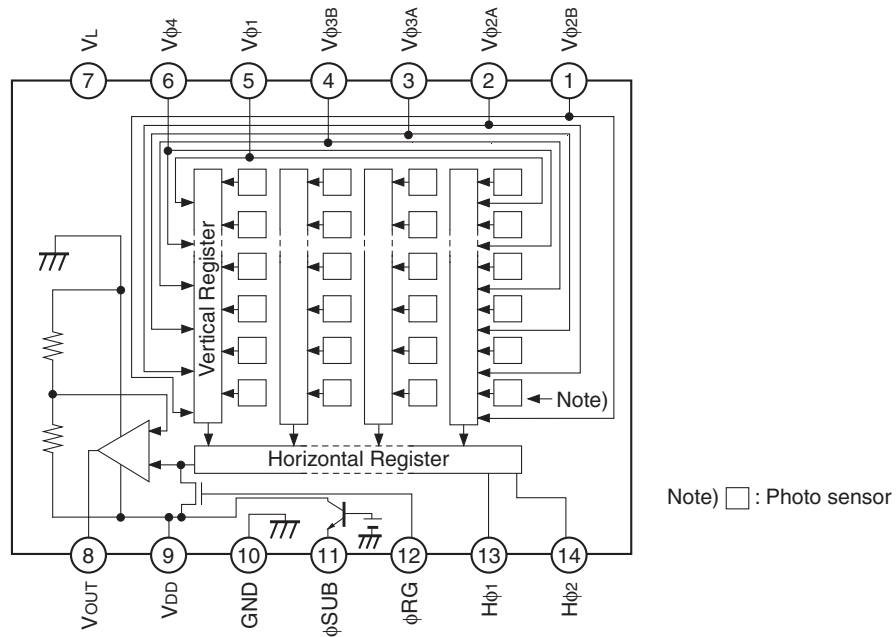
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Block Diagram and Pin Configuration

(Top View)



Pin Description

Pin No.	Symbol	Description
1	Vφ2B	Vertical register transfer clock
2	Vφ2A	Vertical register transfer clock
3	Vφ3A	Vertical register transfer clock
4	Vφ3B	Vertical register transfer clock
5	Vφ1	Vertical register transfer clock
6	Vφ4	Vertical register transfer clock
7	VL	Protective transistor bias
8	VOUT	Signal output
9	VDD	Supply voltage
10	GND	GND
11	φSUB	Substrate clock
12	φRG	Reset gate clock
13	Hφ1	Horizontal register transfer clock
14	Hφ2	Horizontal register transfer clock

Absolute Maximum Ratings

Item		Ratings	Unit	Remarks
Against ϕ SUB	V_{DD} , V_{OUT} , ϕ RG – ϕ SUB	–40 to +13	V	
	$V\phi_{2A}$, $V\phi_{2B}$, $V\phi_{3A}$, $V\phi_{3B}$ – ϕ SUB	–50 to +15	V	
	$V\phi_1$, $V\phi_4$ – ϕ SUB	–50 to +0.3	V	
	$H\phi_1$, $H\phi_2$, GND – ϕ SUB	–40 to +0.3	V	
Against GND	V_{DD} , V_{OUT} , ϕ RG – GND	–0.3 to +18	V	
	$V\phi_1$, $V\phi_{2A}$, $V\phi_{2B}$, $V\phi_{3A}$, $V\phi_{3B}$, $V\phi_4$ – GND	–10 to +18	V	
	$H\phi_1$, $H\phi_2$ – GND	–10 to +5	V	
Against V_L	$V\phi_{2A}$, $V\phi_{2B}$, $V\phi_{3A}$, $V\phi_{3B}$ – V_L	–0.3 to +28	V	
	$V\phi_1$, $V\phi_4$, $H\phi_1$, $H\phi_2$ – V_L	–0.3 to +15	V	
Between input clock pins	Potential difference between vertical clock input pins	to +15	V	*1
	$H\phi_1$ – $H\phi_2$	–5 to +5	V	
	$H\phi_1$, $H\phi_2$ – $V\phi_3$	–13 to +13	V	
Storage temperature		–30 to +80	°C	
Operating temperature		–10 to +60	°C	

*1 +24V (Max.) is guaranteed when clock width < 10 μ s, clock duty factor < 0.1%.

Bias Conditions

Item	Symbol	Min.	Typ.	Max.	Unit	Remarks
Supply voltage	V_{DD}	14.55	15.0	15.45	V	
Protective transistor bias	V_L		*1			
Substrate clock	ϕ SUB		*2			
Reset gate clock	ϕ RG		*2			

*1 V_L setting is the V_{VL} voltage of the vertical clock waveform, or the same voltage as the V_L power supply for the V driver should be used.

*2 Do not apply a DC bias to the substrate clock and reset gate clock pins, because a DC bias is generated internally.

DC Characteristics

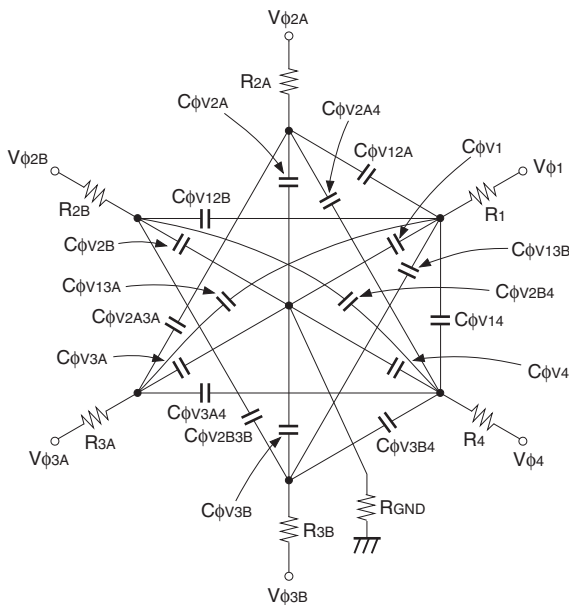
Item	Symbol	Min.	Typ.	Max.	Unit	Remarks
Supply current	I_{DD}		6.0		mA	


Clock Voltage Conditions

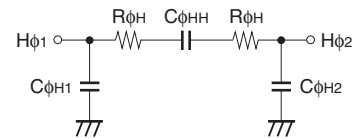
Item	Symbol	Min.	Typ.	Max.	Unit	Waveform diagram	Remarks
Readout clock voltage	V _{VT}	14.55	15.0	15.45	V	1	
Vertical transfer clock voltage	V _{VH02A}	-0.05	0	0.05	V	2	V _{VH} = V _{VH02A}
	V _{VH1} , V _{VH2} (A, B), V _{VH3} (A, B), V _{VH4}	-0.2	0	0.05	V	2	
	V _{VL1} , V _{VL2} (A, B), V _{VL3} (A, B), V _{VL4}	-5.8	-5.5	-5.2	V	2	V _{VL} = (V _{VL1} + V _{VL3} (A, B))/2
	V _{φ1} , V _{φ2} (A, B), V _{φ3} (A, B), V _{φ4}	5.0	5.5	5.85	V	2	
	V _{VL3} (A, B), V _{VL4} - V _{VL}			0.1	V	2	
	V _{VHH}			0.3	V	2	High-level coupling
	V _{VHL}			1.0	V	2	High-level coupling
	V _{VLH}			0.5	V	2	Low-level coupling
	V _{VLL}			0.5	V	2	Low-level coupling
Horizontal transfer clock voltage	V _{φH}	3.0	3.3	5.25	V	3	
	V _H L	-0.05	0	0.05	V	3	
Reset gate clock voltage	V _{φRG}	3.0	3.3	5.5	V	4	
	V _{RGLH} - V _{RGLL}			0.4	V	4	Low-level coupling
	V _{RGL} - V _{RGLm}			0.5	V	4	Low-level coupling
Substrate clock voltage	V _{φSUB}	19.75	20.5	21.25	V	5	

Clock Equivalent Circuit Constants

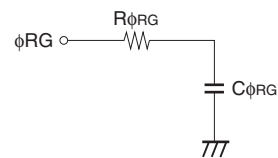
Item	Symbol	Min.	Typ.	Max.	Unit	Remarks
Capacitance between vertical transfer clock and GND	$C\phi V1$		1000		pF	
	$C\phi V2A, C\phi V2B$		820		pF	
	$C\phi V3A, C\phi V3B$		390		pF	
	$C\phi V4$		1500		pF	
Capacitance between vertical transfer clocks	$C\phi V12A, C\phi V12B$		56		pF	
	$C\phi V13A, C\phi V13B$		2		pF	
	$C\phi V14$		180		pF	
	$C\phi V2A3A, C\phi V2B3B$		220		pF	
	$C\phi V2A4, C\phi V2B4$		270		pF	
	$C\phi V3A4, C\phi V3B4$		180		pF	
Capacitance between horizontal transfer clock and GND	$C\phi H1$		15		pF	
	$C\phi H2$		15		pF	
Capacitance between horizontal transfer clocks	$C\phi HH$		47		pF	
Capacitance between reset gate clock and GND	$C\phi RG$		5		pF	
Capacitance between substrate clock and GND	$C\phi SUB$		270		pF	
Vertical transfer clock series resistor	$R1$		47		Ω	
	$R2A, R2B$		91		Ω	
	$R3A, R3B$		68		Ω	
	$R4$		24		Ω	
Vertical transfer clock ground resistor	R_{GND}		47		Ω	
Horizontal transfer clock series resistor	$R\phi H1, R\phi H2$		15		Ω	
Reset gate clock series resistor	$R\phi RG$		56		Ω	



Vertical transfer clock equivalent circuit



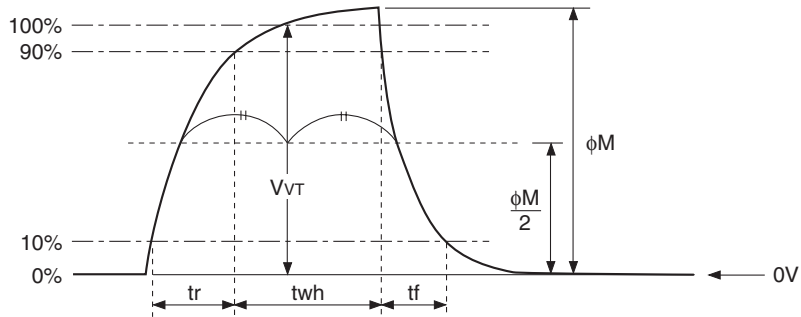
Horizontal transfer clock equivalent circuit



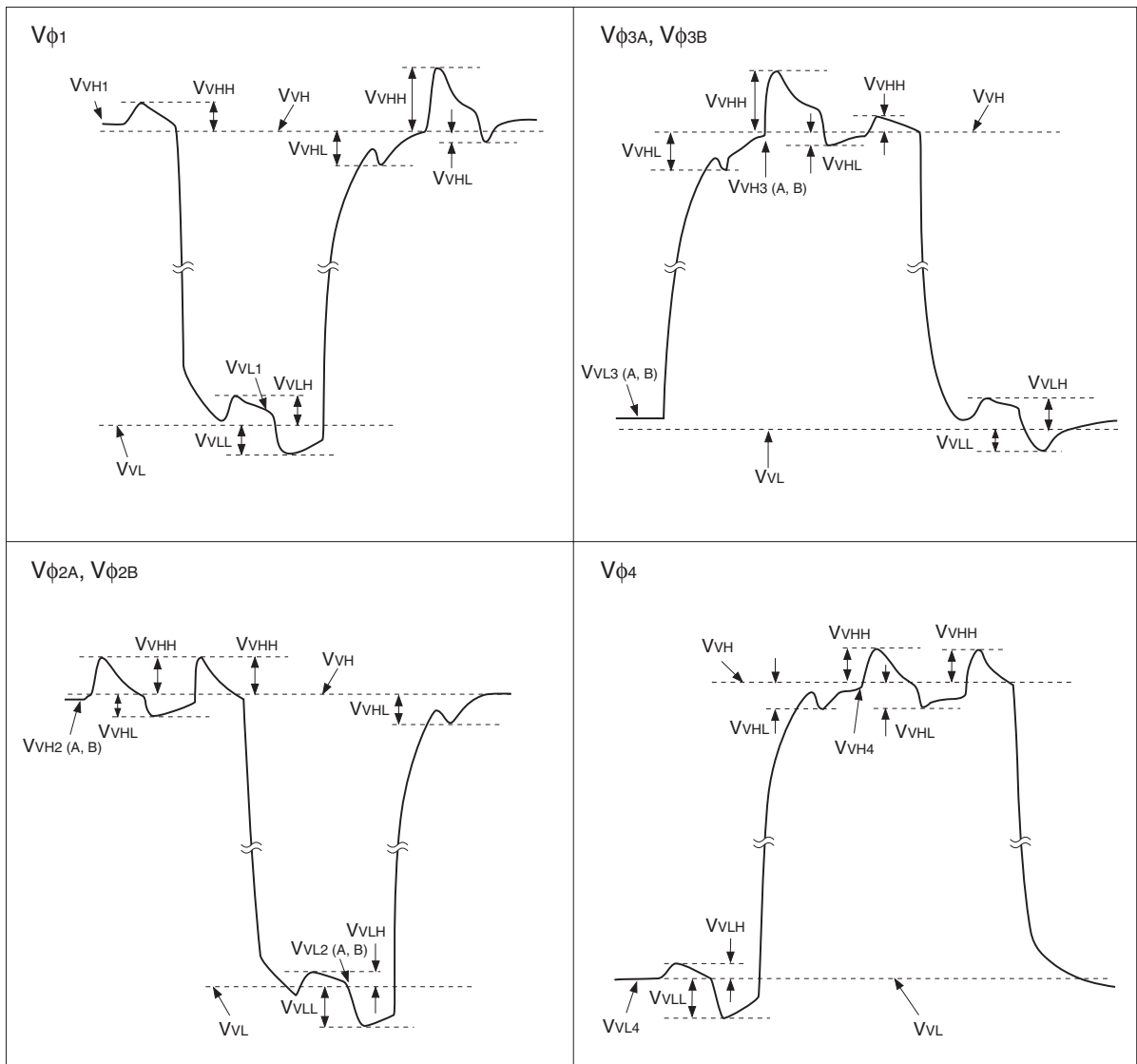
Reset gate clock equivalent circuit

Drive Clock Waveform Conditions

1. Readout clock waveform



2. Vertical transfer clock waveform

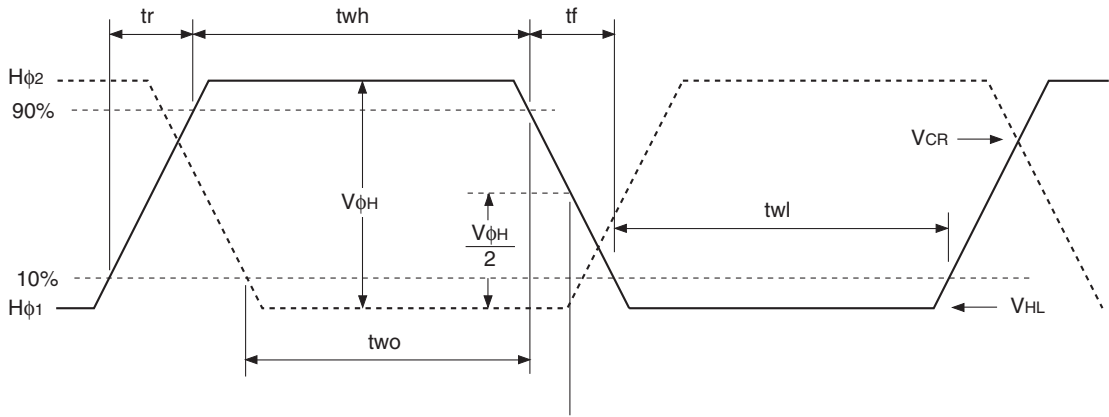


$$V_{VH} = (V_{VH1} + V_{VH2(A, B)})/2$$

$$V_{VL} = (V_{VVL3(A, B)} + V_{VVL4})/2$$

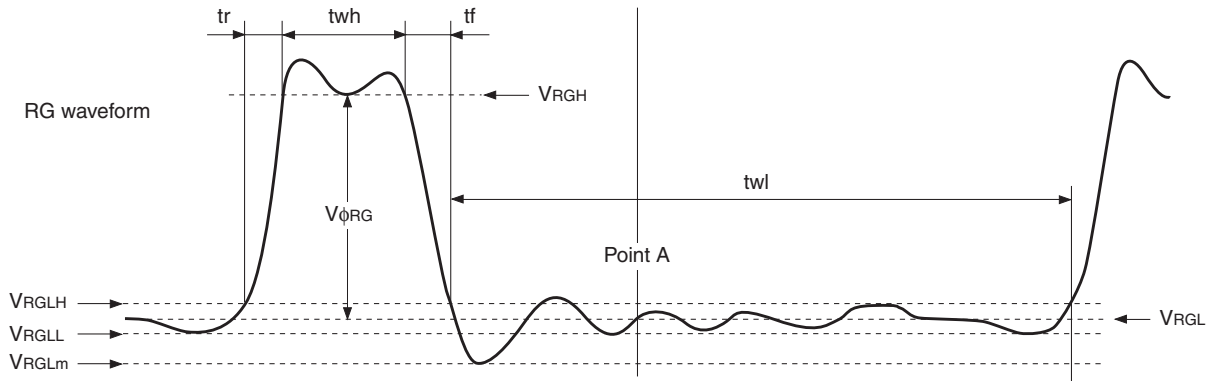
$$V_{\phi V} = V_{VHn} - V_{VVLn} \quad (n = 1 \text{ to } 4)$$

3. Horizontal transfer clock waveform



Cross-point voltage for the $H\phi_1$ rising side of the horizontal transfer clocks $H\phi_1$ and $H\phi_2$ waveforms is V_{CR} . The overlap period for t_{wh} and t_{wl} of horizontal transfer clocks $H\phi_1$ and $H\phi_2$ is "two".

4. Reset gate clock waveform



V_{RGLH} is the maximum value and V_{RGLL} is the minimum value of the coupling waveform during the period from Point A in the above diagram until the rising edge of RG.

In addition, V_{RGL} is the average value of V_{RGLH} and V_{RGLL} .

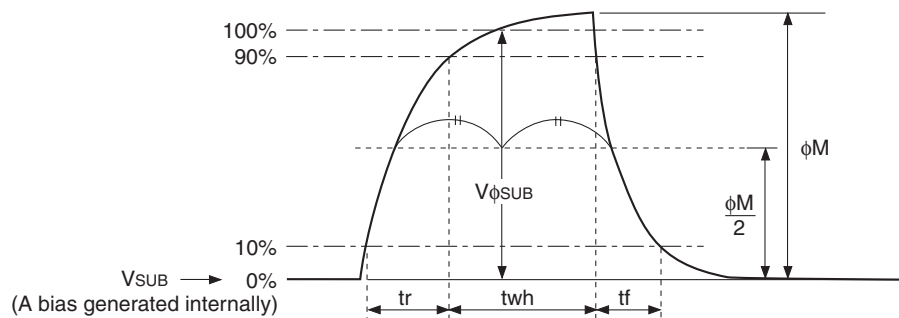
$$V_{RGL} = (V_{RGLH} + V_{RGLL})/2$$

Assuming V_{RGH} is the minimum value during the interval t_{wh} , then:

$$V_{\phi RG} = V_{RGH} - V_{RGL}$$

Negative overshoot level during the falling edge of RG is V_{RGLm} .

5. Substrate clock waveform



Clock Switching Characteristics

Item	Symbol	twh			twl			tr			tf			Unit	Remarks
		Min.	Typ.	Max.	Min.	Typ.	Max.	Min.	Typ.	Max.	Min.	Typ.	Max.		
Readout clock	V _T	1.8	2.0						0.5			0.5		μs	During readout
Vertical transfer clock	V _{φ1} , V _{φ2(A,B)} , V _{φ3(A,B)} , V _{φ4}										15		250	ns	*1
Horizontal transfer clock	During imaging	H _{φ1}	10.5	14.6		10.5	14.6		6.4	10.5		6.4	10.5	ns	*2
		H _{φ2}	10.5	14.6		10.5	14.6		6.4	10.5		6.4	10.5		
	During parallel-serial conversion	H _{φ1}							0.001					μs	
		H _{φ2}							0.001						
Reset gate clock	φ _{RG}	6	8			25.8		4			3		ns		
Substrate clock	φ _{SUB}	0.63	0.73						0.5			0.5	μs	When draining charge	

*1 When vertical transfer clock driver CXD1267AN is used.

*2 $t_f \geq t_r - 2\text{ns}$, and the cross-point voltage (V_{CR}) for the H_{φ1} rising side of the H_{φ1} and H_{φ2} waveforms must be at least $V_{\phi H/2}$ [V].

Item	Symbol	two			Unit	Remarks
		Min.	Typ.	Max.		
Horizontal transfer clock	H _{φ1} , H _{φ2}	10.5	14.6		ns	

Spectral Sensitivity Characteristics

(excludes lens characteristics and light source characteristics)

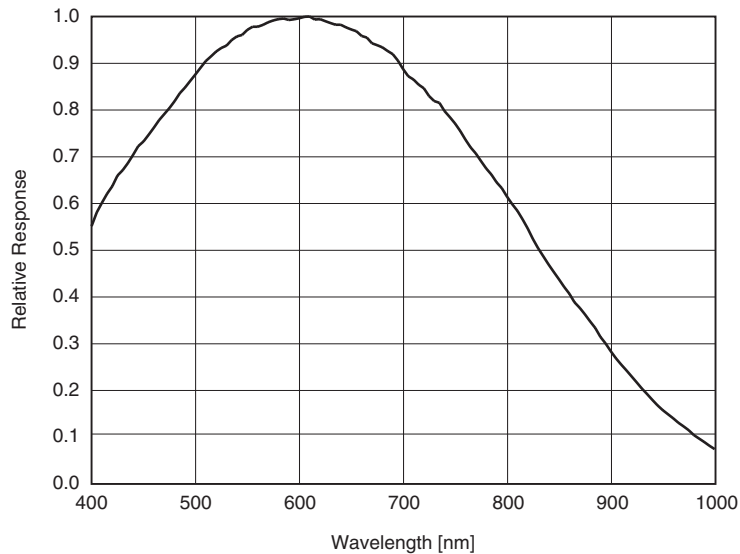
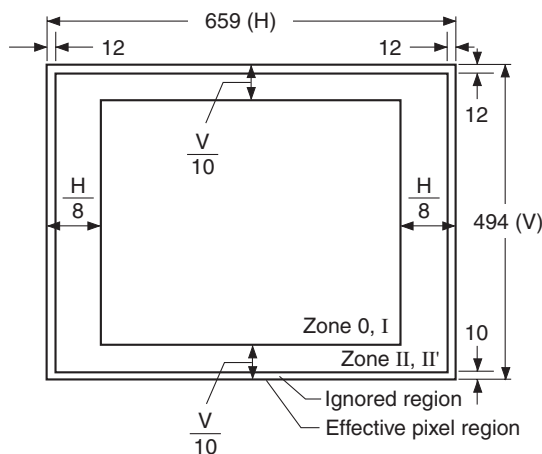


Image Sensor Characteristics

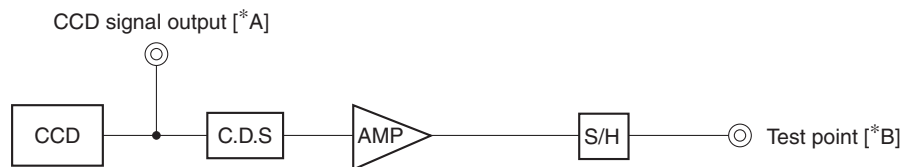
(Ta = 25°C)

Item	Symbol	Min.	Typ.	Max.	Unit	Measurement method	Remarks
Sensitivity 1	S1	960	1200		mV	1	1/30s accumulation
Sensitivity 2	S2		5500		mV	2	1/30s accumulation
Saturation signal	Vsat	800			mV	3	Ta = 60°C
Smear	Sm	-100	-110		dB	4	
Video signal shading	SH			20	%	5	Zone 0 and I
				25	%	5	Zone 0 to II'
Dark signal	Vdt			4	mV	6	Ta = 60°C, 1/30s accumulation
Dark signal shading	ΔVdt			1	mV	7	Ta = 60°C, 1/30s accumulation
Lag	Lag			0.5	%	8	

Zone Definition of Video Signal Shading



Measurement System



Note) Adjust the amplifier gain so that the gain between [*A] and [*B] equals 1.

Image Sensor Characteristics Measurement Method

Measurement conditions

1. In the following measurements, the device drive conditions are at the typical values of the bias and clock voltage conditions.
2. In the following measurements, spot pixels are excluded and, unless otherwise specified, the optical black level (OB) is used as the reference for the signal output, which is taken as the value measured at point [*B] of the measurement system.

Definition of standard imaging conditions

- ◆ Standard imaging condition I:
Use a pattern box (luminance: 706cd/m², color temperature of 3200K halogen source) as a subject. (Pattern for evaluation is not applicable.) Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter and image at F8. The luminous intensity to the sensor receiving surface at this point is defined as the standard sensitivity testing luminous intensity.
- ◆ Standard imaging condition II:
This indicates the standard imaging condition I with the IR cut filter removed.
- ◆ Standard imaging condition III:
Image a light source (color temperature of 3200K) with a uniformity of brightness within 2% at all angles. Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter. The luminous intensity is adjusted to the value indicated in each testing item by the lens diaphragm.

1. Sensitivity 1

Set to the standard imaging condition I. After setting the electronic shutter mode with a shutter speed of 1/100s, measure the signal output (Vs) at the center of the screen and substitute the value into the following formula.

$$S = V_s \times (100/30) \text{ [mV]}$$

2. Sensitivity 2

Set to the standard imaging condition II. After setting the electronic shutter mode with a shutter speed of 1/1000s, measure the signal output (Vs2) at the center of the screen and substitute the value into the following formula.

$$S_2 = V_{s2} \times (1000/30) \text{ [mV]}$$

3. Saturation signal

Set to the standard imaging condition III. After adjusting the luminous intensity to 10 times the intensity with the average value of the signal output, 150mV, measure the minimum value of the signal output.

4. Smear

Set to the standard imaging condition III. With the lens diaphragm at F5.6 to F8, first adjust the average value of the signal output to 150mV. After the readout clock is stopped and the charge drain is executed by the electronic shutter at the respective H blankings, measure the maximum value (Vsm [mV]) of the signal output, and substitute the value into the following formula.

$$S_m = 20 \times \log \{ (V_{sm}/150) \times (1/500) \times (1/10) \} \text{ [dB]} \quad (1/10V \text{ method conversion value})$$

5. Video signal shading

Set to the standard imaging condition III. With the lens diaphragm at F5.6 to F8, adjusting the luminous intensity so that the average value of the signal output is 150mV. Then measure the maximum value (Vmax [mV]) and minimum value (Vmin [mV]) of the signal and substitute the values into the following formula.

$$SH = (V_{max} - V_{min})/150 \times 100 [\%]$$

6. Dark signal

Measure the average value of the signal output (Vdt [mV]) with the device ambient temperature of 60°C and the device in the light-obstructed state, using the horizontal idle transfer level as a reference.

7. Dark signal shading

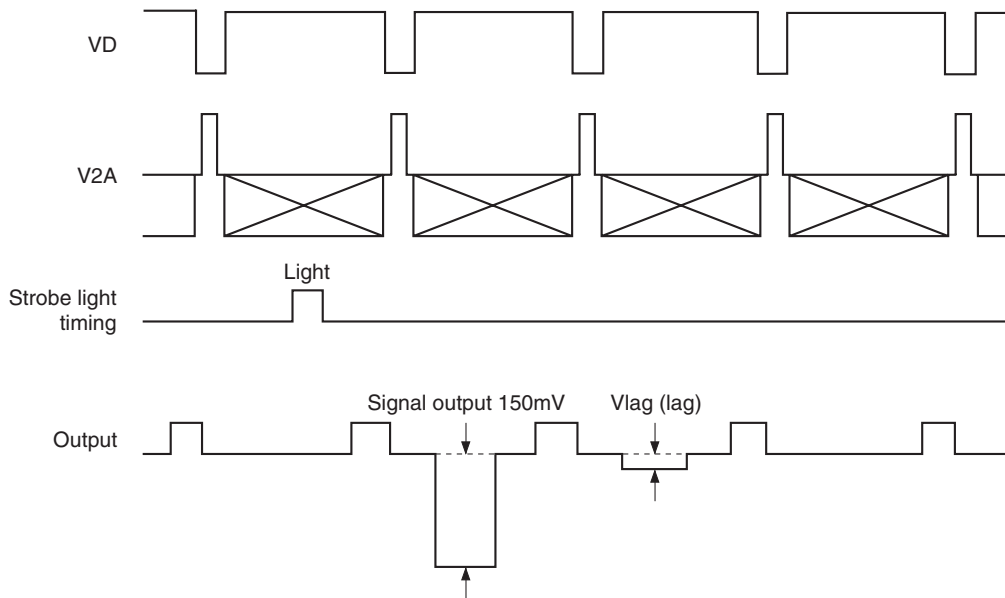
After the measurement item 6, measure the maximum (Vdmax [mV]) and minimum (Vdmin [mV]) values of the dark signal output and substitute the values into the following formula.

$$\Delta V_{dt} = V_{dmax} - V_{dmin} [mV]$$

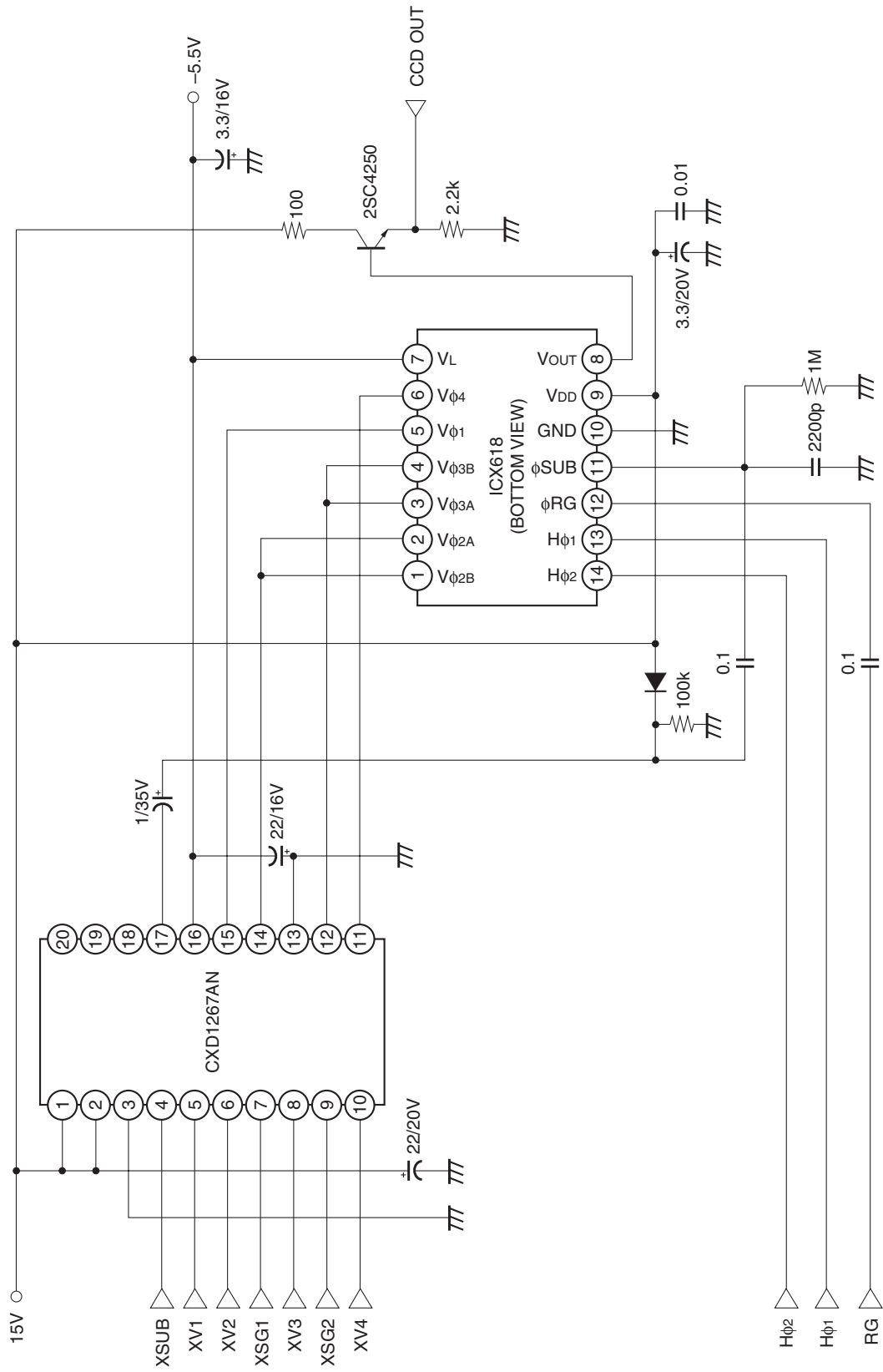
8. Lag

Adjust the signal output value generated by strobe light to 150mV. After setting the strobe light so that it strobes with the following timing, measure the residual signal (Vlag). Substitute the value into the following formula.

$$Lag = (V_{lag}/150) \times 100 [\%]$$

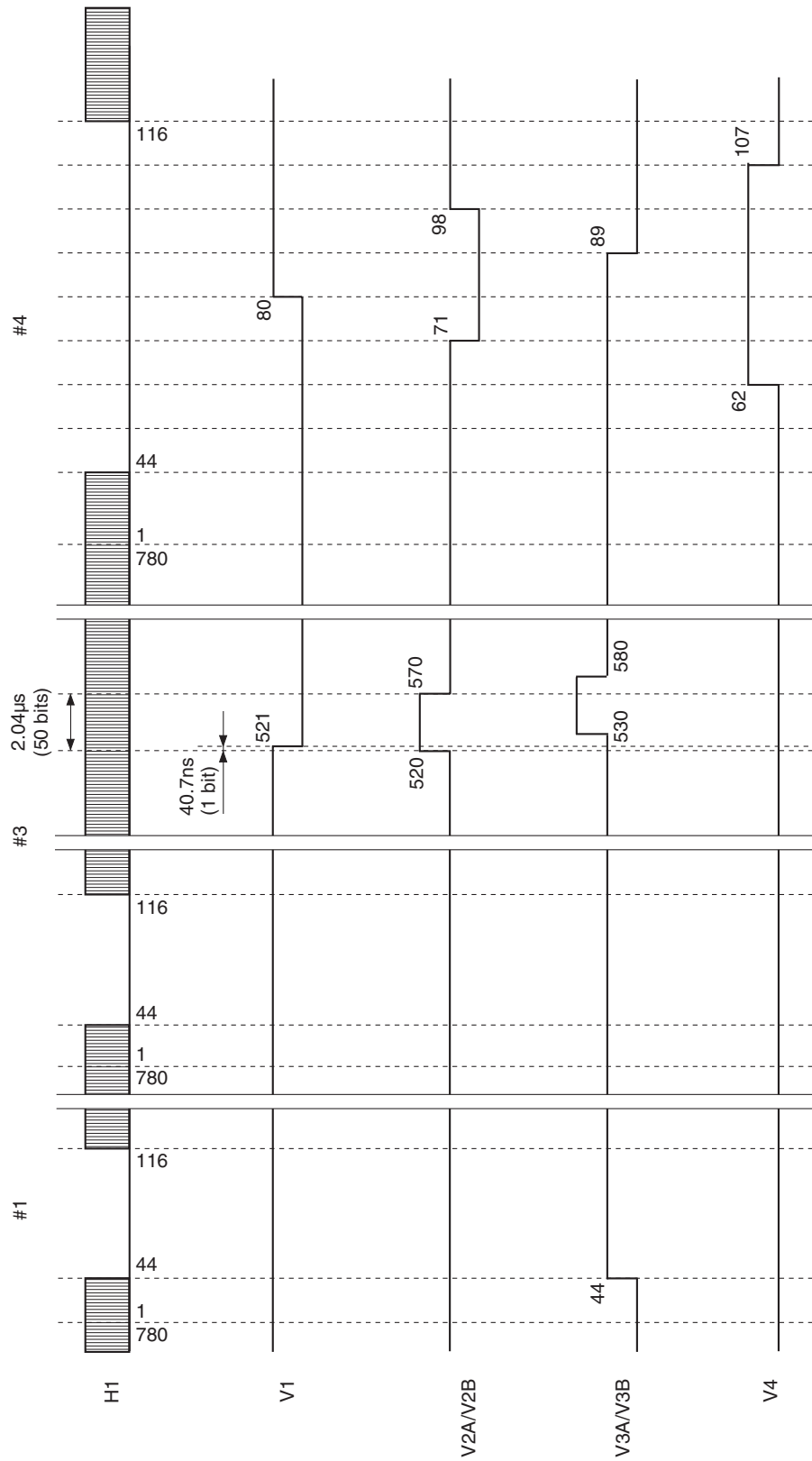


Drive Circuit



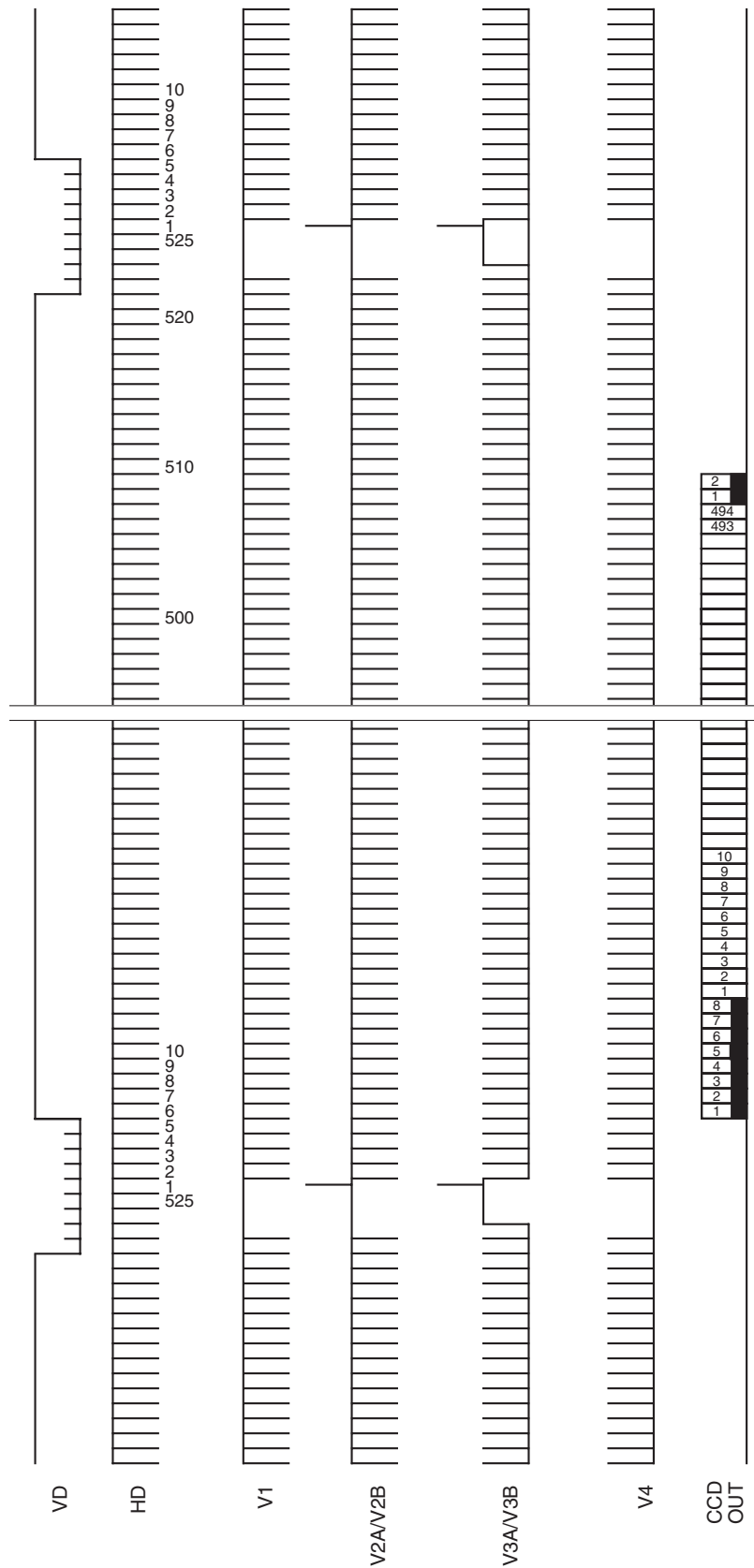
Drive Timing Chart

Readout Portion



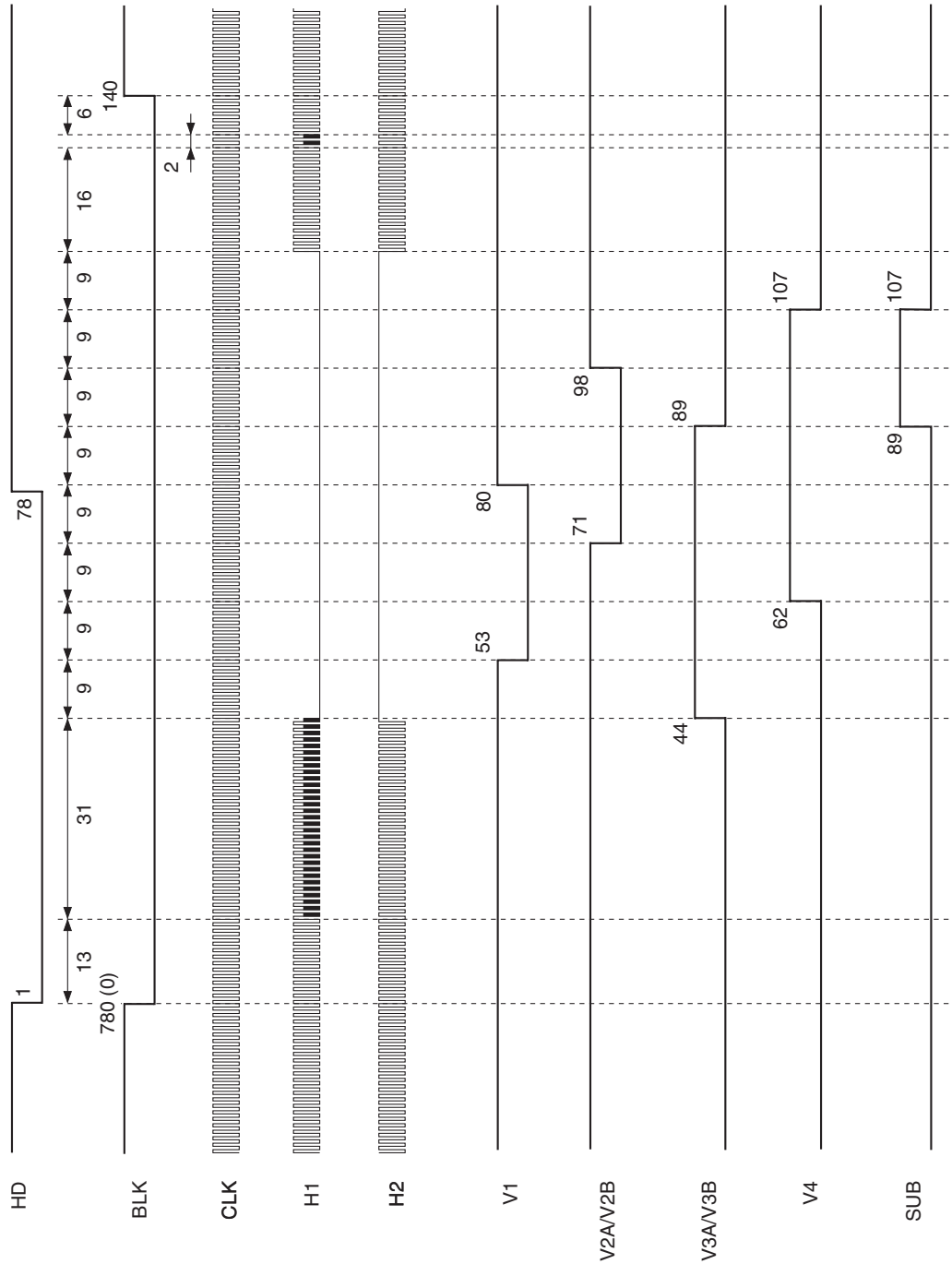
Drive Timing Chart

Vertical Sync



Drive Timing Chart

Horizontal Sync



Notes On Handling

1. Static charge prevention

Image sensors are easily damaged by static discharge. Before handling be sure to take the following protective measures.

- (1) Either handle bare handed or use non-chargeable gloves, clothes or material. Also use conductive shoes.
- (2) Use a wrist strap when handling directly.
- (3) Install grounded conductive mats on the floor and working table to prevent the generation of static electricity.
- (4) Ionized air is recommended for discharge when handling image sensors.
- (5) For the shipment of mounted boards, use boxes treated for the prevention of static charges.

2. Soldering

- (1) Make sure the temperature of the upper surface of the seal glass resin adhesive portion of the package does not exceed 80°C.
- (2) Solder dipping in a mounting furnace causes damage to the glass and other defects. Use a 30W soldering iron with a ground wire and solder each pin in 2 seconds or less. For repairs and remount, cool sufficiently.
- (3) To dismount an image sensor, do not use solder suction equipment. When using an electric desoldering tool, use a thermal controller of the zero-cross On/Off type and connect it to ground.

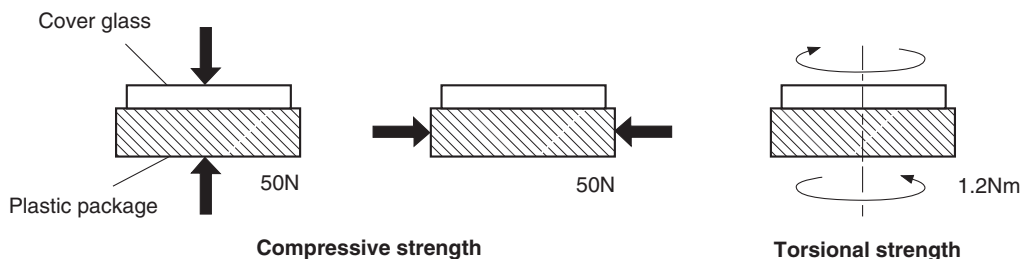
3. Protection from dust and dirt

Image sensors are packed and delivered with care taken to protect the element glass surfaces from harmful dust and dirt. Clean glass surfaces with the following operations as required before use.

- (1) Perform all lens assembly and other work in a clean room (class 1000 or less).
- (2) Do not touch the glass surface with hand and make any object contact with it. If dust or other is stuck to a glass surface, blow it off with an air blower. (For dust stuck through static electricity, ionized air is recommended.)
- (3) Clean with a cotton bud and ethyl alcohol if grease stained. Be careful not to scratch the glass.
- (4) Keep in a dedicated case to protect from dust and dirt. To prevent dew condensation, preheat or precool when moving to a room with great temperature differences.
- (5) When a protective tape is applied before shipping, remove the tape applied for electrostatic protection just before use. Do not reuse the tape.

4. Installing (attaching)

- (1) Remain within the following limits when applying a static load to the package. Do not apply any load more than 0.7mm inside the outer perimeter of the glass portion, and do not apply any load or impact to limited portions. (This may cause cracks in the package.)

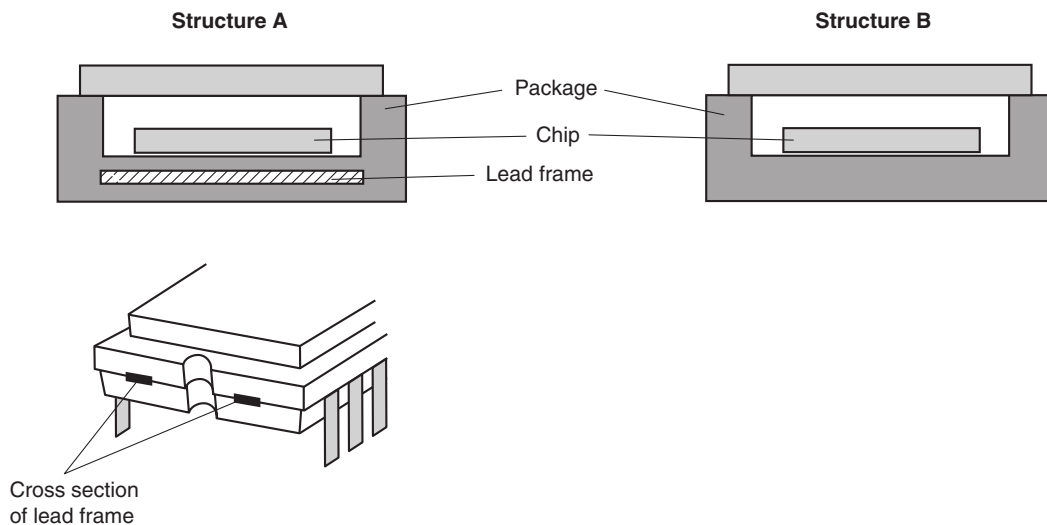


- (2) If a load is applied to the entire surface by a hard component, bending stress may be generated and the package may fracture, etc., depending on the flatness of the bottom of the package. Therefore, for installation, use either an elastic load, such as a spring plate, or an adhesive.
- (3) The adhesive may cause the marking on the rear surface to disappear, especially in case the regulated voltage value is indicated on the rear surface. Therefore, the adhesive should not be applied to this area, and indicated values should be transferred to the other locations as a precaution.

- (4) The notch of the package is used for directional index, and that can not be used for reference of fixing. In addition, the cover glass and seal resin may overlap with the notch of the package.
- (5) If the lead bend repeatedly and the metal, etc., clash or rub against the package, dust may be generated by the fragments of resin.
- (6) Acrylate anaerobic adhesives are generally used to attach image sensors. In addition, cyanoacrylate instantaneous adhesives are sometimes used jointly with acrylate anaerobic adhesives to hold the image sensor in place until the adhesive completely hardens. (reference)

5. Others

- (1) Do not expose to strong light (sun rays) for long periods, as color filters will be discolored. When high luminance objects are imaged with the exposure level controlled by the electronic iris, the luminance of the image-plane may become excessive and discoloration of the color filters may be accelerated. In such a case, arrangements such as using an automatic iris with the imaging lens or automatically closing the shutter during power-off are advisable. For continuous use under harsh conditions exceeding the normal conditions of use, consult your Sony representative.
- (2) Exposure to high temperature or humidity will affect the characteristics. Accordingly avoid storage or use in such conditions.
- (3) Brown stains may be seen on the bottom or side of the package. But this does not affect the characteristics.
- (4) This package has 2 kinds of internal structure. However, their package outline, optical size, and strength are the same.
- (5) This image sensor has sensitivity in the near infrared area. Its focus may not match in the same condition under visible light/near infrared light because of aberration. Incident light component of long wavelength which transmits the silicon substrate may have bad influence upon image.

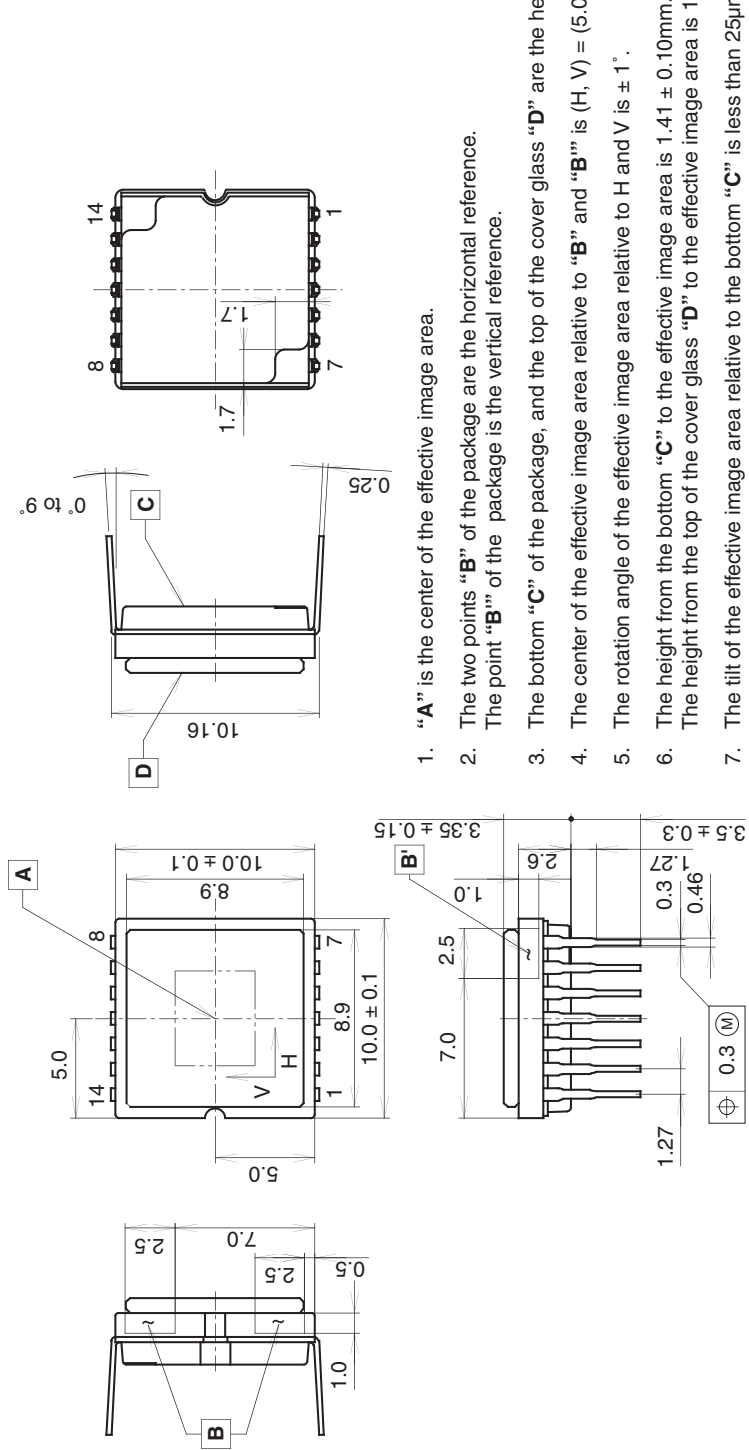


The cross section of lead frame can be seen on the side of the package for structure A.

Package Outline

(Unit: mm)

14 pin DIP (400mil)



1. "A" is the center of the effective image area.
2. The two points "B" of the package are the horizontal reference. The point "B" of the package is the vertical reference.
3. The bottom "C" of the package, and the top of the cover glass "D" are the height reference.
4. The center of the effective image area relative to "B" and "B'" is $(H, V) = (5.0, 5.0) \pm 0.15$ mm.
5. The rotation angle of the effective image area relative to H and V is $\pm 1^\circ$.
6. The height from the bottom "C" to the effective image area is 1.41 ± 0.10 mm. The height from the top of the cover glass "D" to the effective image area is 1.94 ± 0.15 mm.
7. The tilt of the effective image area relative to the bottom "C" is less than $25\mu\text{m}$. The tilt of the effective image area relative to the top "D" of the cover glass is less than $25\mu\text{m}$.
8. The thickness of the cover glass is 0.75mm, and the refractive index is 1.5.
9. The notch of the package is used only for directional index, that must not be used for reference of fixing.
10. Cover glass defect
Edge part
Length : no matter, Width : less than 0.5mm, Depth : less than the thickness of the glass.
Corner part
Length : less than 1.5mm, Depth : less than the thickness of the glass.

PACKAGE STRUCTURE

PACKAGE MATERIAL	Plastic
LEAD TREATMENT	GOLD PLATING
LEAD MATERIAL	42 ALLOY
PACKAGE MASS	0.60g
DRAWING NUMBER	AS-D3-02(E)